Learning Deep Broadband Network@HOME

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Who am I?

- Machine Learning Engineer
 - Fraud Detection System
 - Software Defect Prediction
- Software Engineer
 - Email Services (40+ mil. users)
 - High traffic server (IPC, network, concurrent programming)
- MPhil, HKUST
 - Major : Software Engineering based on ML tech
 - Research interests : ML, NLP, IR

Outline

Data Collection	Time series Analysis	Forecast Modeling	Anomaly Detection
			Naive approach
Logging SpeedTest Data preparation Handling time series	Seasonal Trend Decomposition	Rolling Forecast	Basic approaches
	Stationarity Autoregression, Moving Average Autocorrelation	ARIMA	Multivariate Gaussian
		LSTM	

Home Network



Home Network



Home Network



Anomaly Detection (Naive approach in 2015)



Problem definition

- Detect abnormal states of Home Network
- Anomaly detection for time series
 - Finding outlier data points relative to some usual signal

Types of anomalies in time series

• Additive outliers



Types of anomalies in time series

• Temporal changes



Types of anomalies in time series

• Level shift



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Logging Data

• Speedtest-cli

```
$ speedtest-cli --simple
Ping: 35.811 ms
Download: 68.08 Mbit/s
Upload: 19.43 Mbit/s
$ crontab -1
*/5 * * * echo `>>> `$(date) >> $LOGFILE; speedtest-cli --simple >> $LOGFILE
2>&1
```

• Every 5 minutes for 3 Month. \Rightarrow 20k observations.

Logging Data

• Log output

\$ more \$LOGFILE >>> Thu Apr 13 10:35:01 KST 2017 Ping: 42.978 ms Download: 47.61 Mbit/s Upload: 18.97 Mbit/s >>> Thu Apr 13 10:40:01 KST 2017 Ping: 103.57 ms Download: 33.11 Mbit/s Upload: 18.95 Mbit/s >>> Thu Apr 13 10:45:01 KST 2017 Ping: 47.668 ms Download: 54.14 Mbit/s Upload: 4.01 Mbit/s

• Parse data

```
def __iter__(self):
    return self
```

```
def next(self):
```

```
...
```

• Build panda DataFrame

df = pd.DataFrame(index=dt_index,

data=([st.ping, st.download, st.upload] for st in speedtests), columns=['ping','down','up'])

• Plot raw data



- Structural breaks
 - Accidental missings for a long period



- Handling missing data
 - \circ Only a few occasional cases

In [147]:		df[df.ping.isnull()]				
Out	[147]:		ping	down	up	
		2017-04-15 14:55:00	NaN	NaN	NaN	
	2017-04-16 07:50:00	NaN	NaN	NaN		
	2017-04-16 08:15:00	NaN	NaN	NaN		
	2017-04-19 17:20:00	NaN	NaN	NaN		
	2017-04-19 22:20:00	NaN	NaN	NaN		
	2017-04-20 00:00:00	NaN	NaN	NaN		

In [148]: df = df.fillna(method='pad', limit=1)

Handling time series

- By DatetimeIndex
 - o df['2017-04':'2017-06']
 - df['2017-04':]
 - o df['2017-04-01 00:00:00':]
 - o df[df.index.weekday_name == 'Monday']
 - df[df.index.minute == 0]
- By TimeGrouper
 - df.groupby(pd.TimeGrouper('D'))
 - df.groupby(pd.TimeGrouper('M'))

Patterns in time series

• Is there a pattern in 24 hours?



Patterns in time series

• Is there a daily pattern?



Components of Time series data

- Trend : The increasing or decreasing direction in the series.
- Seasonality : The repeating in a period in the series.
- Noise : The random variation in the series.

Components of Time series data

- A time series is a combination of these components.
 - $\circ \qquad y_t = T_t + S_t + N_t \text{ (additive model)}$
 - $\circ \quad y_t = T_t \times S_t \times N_t \text{ (multiplicative model)}$

Seasonal Trend Decomposition

from statsmodels.tsa.seasonal import seasonal_decompose
decomposition = seasonal_decompose(week_dn_ts)



Rolling Forecast



Rolling Forecast

from statsmodels.tsa.arima_model import ARIMA

```
forecasts = list()
history = [x for x in train_X]
for t in range(len(test_X)):  # for each new observation
    model = ARIMA(history, order=order) # update the model
    y_hat = model.fit().forecast()  # forecast one step ahead
    forecasts.append(y_hat)  # store predictions
    history.append(test X[t])  # keep history updated
```

Residuals ~ N(μ , σ^2)

residuals = [test[t] - forecasts[t] for t in range(len(test_X))]
residuals = pd.DataFrame(residuals)
residuals.plot(kind='kde')



- IQR (Inter Quartile Range)
- 2-5 Standard Deviation
- MAD (Median Absolute Deviation)

• Inter Quartile Range



- Inter Quartile Range
 - NumPy

```
q1, q3 = np.percentile(col, [25, 75])
iqr = q3 - q1
np.where((col < q1 - 1.5*iqr) | (col > q3 + 1.5*iqr))
```

• Pandas

```
q1 = df['col'].quantile(.25)
q3 = df['col'].quantile(.75)
iqr = q3 - q1
df.loc[~df['col'].between(q1-1.5*iqr, q3+1.5*iqr),'col']
```

• 2-5 Standard Deviation



- 2-5 Standard Deviation
 - NumPy

```
std = np.std(col)
med = np.median(col)
np.where((col < med - 3*std) | (col < med + 3*std))</pre>
```

• Pandas

```
std = pd['col'].std()
med = pd['col'].median()
df.loc[~df['col'].between(med - 3*std, med + 3*std), 0]
```

- MAD (Median Absolute Deviation)
 - MAD = median($|X_i median(X)|$)
 - "Detecting outliers: Do not use standard deviation around the mean, use absolute deviation around the median" - Christopher Leys (2013)

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Stationary Series Criterion

• The mean, variance and covariance of the series are time invariant.



stationary

non-stationary

Stationary Series Criterion

• The mean, **variance** and covariance of the series are time invariant.



Stationary Series Criterion

• The mean, variance and <u>covariance</u> of the series are time invariant.



Test Stationarity

Differencing

- A non-stationary series can be made stationary after differencing.
- Instead of modelling the level, we model the change
- Instead of forecasting the level, we forecast the change
- $I(d) = y_t y_{t-d}$
- AR + I + MA

Autoregression (AR)

- Autoregression means developing a linear model that uses observations at previous time steps to predict observations at future time step.
- Because the regression model uses data from the same input variable at previous time steps, it is referred to as an autoregression

Moving Average (MA)

- MA models look similar to the AR component, but it's dealing with different values.
- The model account for the possibility of a relationship between a variable and the residuals from previous periods.

ARIMA(p, d, q)

- Autoregressive Integrated Moving Average
 - AR : A model that uses dependent relationship between an observation and some number of lagged observations.
 - I : The use of differencing of raw observations in order to make the time series stationary.
 - MA : A model that uses the dependency between an observation and a residual error from a MA model.
- parameters of ARIMA model
 - p: The number of lag observations included in the model
 - d: the degree of differencing, the number of times that raw observations are differenced
 - q : The size of moving average window.

Identification of ARIMA

- Autocorrelation function(ACF) : measured by a simple correlation between current observation Y_t and the observation p lags from the current one Y_{t-p}.
- Partial Autocorrelation Function (PACF) : measured by the degree of association between Y_t and Y_{t-p} when the effects at other intermediate time lags between Y_t and Y_{t-p} are removed.
- Inference from ACF and PACF: theoretical ACFs and PACFs are available for various values of the lags of AR and MA components. Therefore, plotting ACFs and PACFs versus lags and comparing leads to the selection of the appropriate parameter p and q for ARIMA model

Identification of ARIMA (easy case)

• General characteristics of theoretical ACFs and PACFs

model	ACF	PACF
AR(p)	Tail off; Spikes decay towards zero	Spikes cutoff to zero after lag p
MA(q)	Spikes cutoff to zero after lag q	Tails off; Spikes decay towards zero
ARMA(p,q)	Tails off; Spikes decay towards zero	Tails off; Spikes decay towards zero

• Reference :

- <u>http://people.duke.edu/~rnau/411arim3.htm</u>
- Prof. Robert Nau

Identification of ARIMA (easy case)



Identification of ARIMA (complicated)



Anomaly Detection (Parameter Estimation)



Anomaly Detection (Multivariate Gaussian Distribution)



Anomaly Detection (Multivariate Gaussian)

import numpy as np
from scipy.stats import multivariate_normal

```
def estimate_gaussian(dataset):
    mu = np.mean(dataset, axis=0)
    sigma = np.cov(dataset.T)
    return mu, sigma
```

def multivariate_gaussian(dataset, mu, sigma):
 p = multivariate_normal(mean=mu, cov=sigma)
 return p.pdf(dataset)

```
mu, sigma = estimate_gaussian(train_X)
p = multivariate_gaussian(train_X, mu, sigma)
anomalies = np.where(p < ep)  # ep : threshold</pre>
```

$$\mu = \frac{1}{m} \sum_{i=1}^{m} x(i)$$

$$\Sigma = \frac{1}{m} \sum_{i=1}^{m} (x(i) - \mu) \cdot (x(i) - \mu)^{T}$$

Anomaly Detection (Multivariate Gaussian)

import numpy as np
from scipy.stats import multivariate_normal

```
def estimate_gaussian(dataset):
    mu = np.mean(dataset, axis=0)
    sigma = np.cov(dataset.T)
    return mu, sigma
```

$$p(x) = \frac{1}{(2\pi)^{\frac{\pi}{2}} |\Sigma|^{\frac{1}{2}}} exp\left(-\frac{1}{2}(x-\mu)^{T}\Sigma^{-1}(x-\mu)\right)$$

def multivariate_gaussian(dataset, mu, sigma):
 p = multivariate_normal(mean=mu, cov=sigma)
 return p.pdf(dataset)

```
mu, sigma = estimate_gaussian(train_X)
p = multivariate_gaussian(train_X, mu, sigma)
anomalies = np.where(p < ep)  # ep : threshold</pre>
```

Anomaly Detection (Multivariate Gaussian)

import numpy as np
from scipy.stats import multivariate_normal

```
def estimate_gaussian(dataset):
    mu = np.mean(dataset, axis=0)
    sigma = np.cov(dataset.T)
    return mu, sigma
```

```
y = \begin{cases} 1 & if \ P(x_{test}) < \varepsilon \ (anomaly) \\ 0 & if \ P(x_{test}) \ge \varepsilon \ (normal) \end{cases}
```

def multivariate_gaussian(dataset, mu, sigma):
 p = multivariate_normal(mean=mu, cov=sigma)
 return p.pdf(dataset)

```
mu, sigma = estimate_gaussian(train_X)
p = multivariate_gaussian(train_X, mu, sigma)
anomalies = np.where(p < ep)  # ep : threshold</pre>
```

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```
from keras.models import Sequential
from keras.layers import Dense
from keras.layers import LSTM
from sklearn.metrics import mean squared error
model = Sequential()
model.add(LSTM(num neurons, stateful=True, return sequences=True,
                   batch input shape=(batch size, timesteps, input dimension))
model.add(LSTM(num neurons, stateful=True,
                   batch_input_shape=(batch_size, timesteps, input dimension))
model.add(Dense(1))
model.compile(loss='mean squared error', optimizer='adam')
for i in range(num epoch):
    model.fit(train X, y, epochs=1, batch size=batch size, shuffle=False)
```

model.reset_states()

- Will allow to model sophisticated and seasonal dependencies in time series
- Very helpful with multiple time series
- On going research, requires a lot of work to build model for time series

Summary

- Be prepared before calling engineers for service failures
- Pythonista has all the powerful tools
 - **pandas** is great for handling time series
 - **statsmodels** for analyzing and modeling time series
 - **sklearn** is such a multi-tool in data science
 - keras is good to start deep learning
- Pythonista needs to understand a few concepts before using the tools
 - Stationarity in time series
 - Autoregressive and Moving Average
 - Means of forecasting, anomaly detection
- Deep Learning for forecasting time series
 - still on-going research
- Do try this at home

Contacts



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